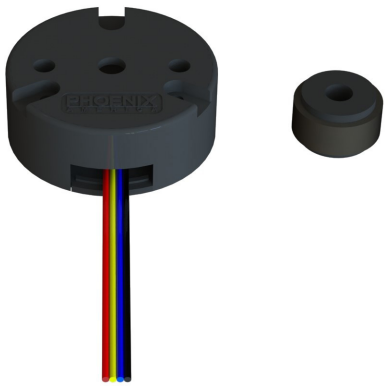
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PHOENIX AMERICA

L2 Series Magnetic Encoder
Low Resolution Kit

Features and Benefits

- 30 mm O.D. Miniature size
- Magnetic technology offers robust performance.
- 100% Non-contacting design (no bearings or bushing) provides an extremely long life expectancy and is tolerant to harsh environments.
- Simple two piece design (target magnet + encoder) for easy alignment and installation.
- Bi-directional two channel incremental quadrature output.
- Mounting holes for 2-bolt (.750 in B.C. x .125 in O.D.) or 3-bolt pattern (.823 in B.C x .078 inch O.D.)
- Target magnet for standard shaft sizes from 2 mm to 3/8 inch. Custom bore size available.
- Options for 4, 6, 8, and 10 pulse per channel per revolution.
- Customizable lead wires, cables, and or connectors.



Kit - Encoder with Target Magnet

Shown with shaft pass through hole

Wire color order varies with part configuration

Application Example

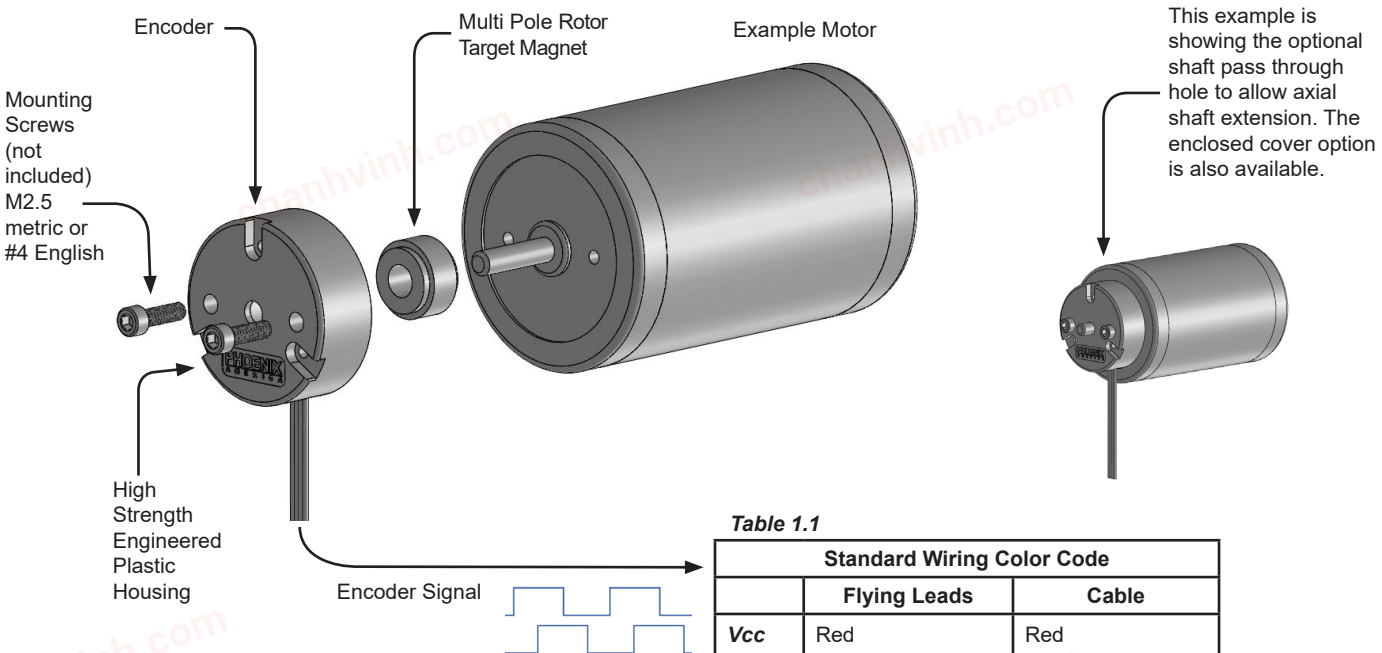


Table 1.1

Standard Wiring Color Code		
	Flying Leads	**Cable**
Vcc	Red	Red
Gnd	Black	Black
Ch A	Yellow	Brown
Ch B	Blue	Orange

Other colors available upon request.
Contact sales@phoenixamerica.com.

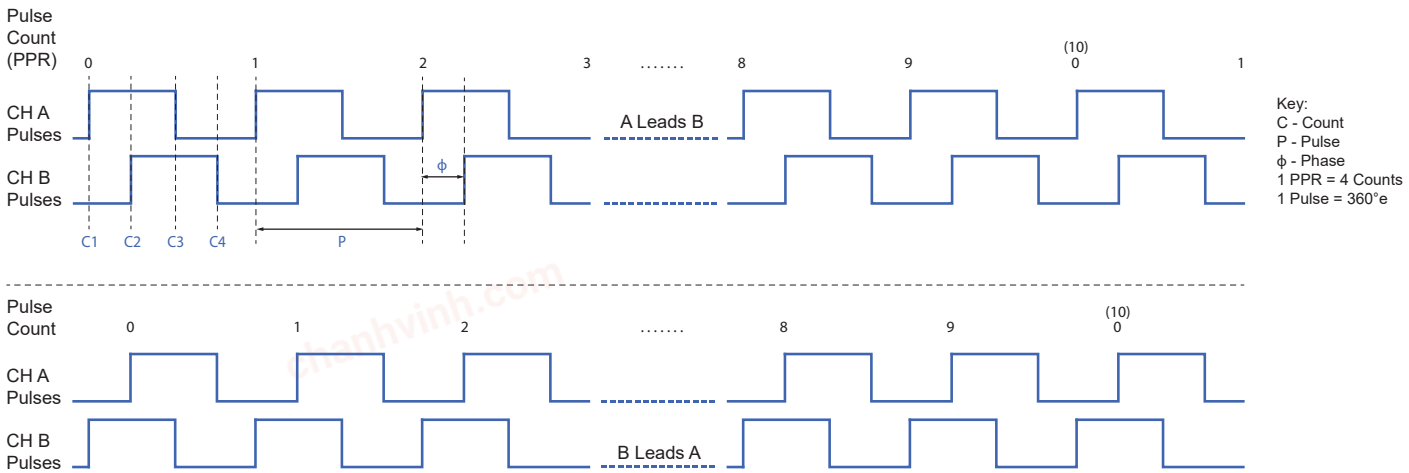
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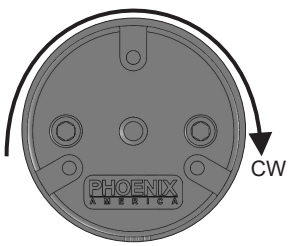
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Output Waveforms





Channel A leads Channel B for clockwise shaft rotation (shaft rotation is defined when looking at the branded face of the encoder).

Absolute Maximum Ratings

Table 2.1

Characteristic	Symbol	Rating	Units
Forward Supply Voltage	V_{CC}	32	V
Reverse Supply Voltage	V_{RCC}	-0.3	V
Output Voltage	V_{OUT}	32	V
Continuous Output Current	I_{OUT}	20	mA
Operating Temperature	T_A	-40 - 125	ºC
Storage Temperature	T_S	-40 - 150	ºC

Electrical Characteristics

Table 2.2

Characteristic	Symbol	Test Conditions	Min.	Typ.[1]	Max.	Unit[2]
Forward Supply Voltage	V_{CC}	Operating, T_J < 165 ºC	4.0	-	24	V
Supply Current	I_{CC}	V_{CC} = 4 to 24V	1.4	3.0	5.6	mA
Output Current	I_{SINK}	V_{CC} = 4 to 24V	-	-	15	mA
Output Frequency	f_{OUT}	V_{CC} = 4 to 24V	-	-	30	kHz

Higher output frequencies available upon request. Contact sales@phoenixamerica.com.

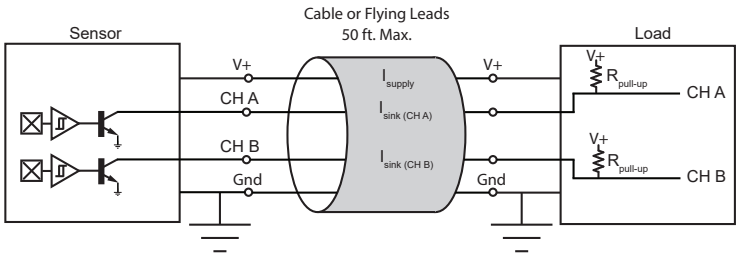
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Electrical Circuit



Output channels require customer supplied pull-up resistors unless internal pull-up option is selected. See Table 3.1 for recommended resistor values.

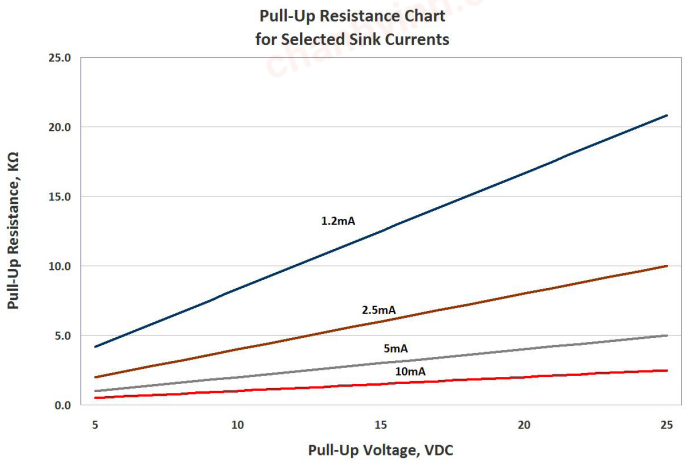


Table 3.1

Recommended Pull-Up Resistor Values			
	Supply Voltage		
Current, I_{sink}	5	12	24
1.2 mA	4.3K	10.0K	20.0K
2.5 mA	2.0K	4.7K	10.0K
5 mA	1.0K	2.4K	4.7K
10 mA	510Ω	1.2K	2.4K

I_{sink} is application dependent. It is recommended to use the lowest possible sink current when selecting a pull-up resistor.

Theoretical Pull-Up Resistor Calculation: $R_{pullup} = \frac{V_{supply}}{I_{sink}}$

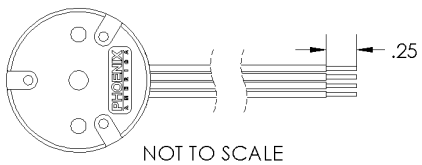
Resistance values based on closest standard 5% resistor values

Absolute Maximum I_{sink} = 20mA

4.7 K pull-up is available as a standard option. If an alternative pull-up value is preferred, contact sales@phoenixamerica.com.

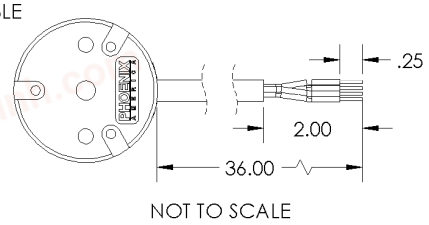
Wiring

FLYING LEADS



- 24 AWG
- 7x32 Strands, Tinned Copper
- PVC Insulation
- UL Type 1430
- Temperature Rating: 105ºC

CABLE



- 24 AWG
- 4 Conductor with Foil Shield and Drain
- Stranded Tinned Copper
- PVC Insulation
- Grey PVC Jacket
- UL Style 2464, CSA
- Temperature Rating: 105ºC

Table 3.2

Standard Wiring			
	Leads	**Cable**	**Connector Pin-Out**
Ch A	Yellow	Brown	1
Ch B	Blue	Orange	2
Gnd	Black	Black	3
Vcc	Red	Red	4

Custom lengths and insulation materials available. Contact sales@phoenixamerica.com.

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Encoder Physical Outline

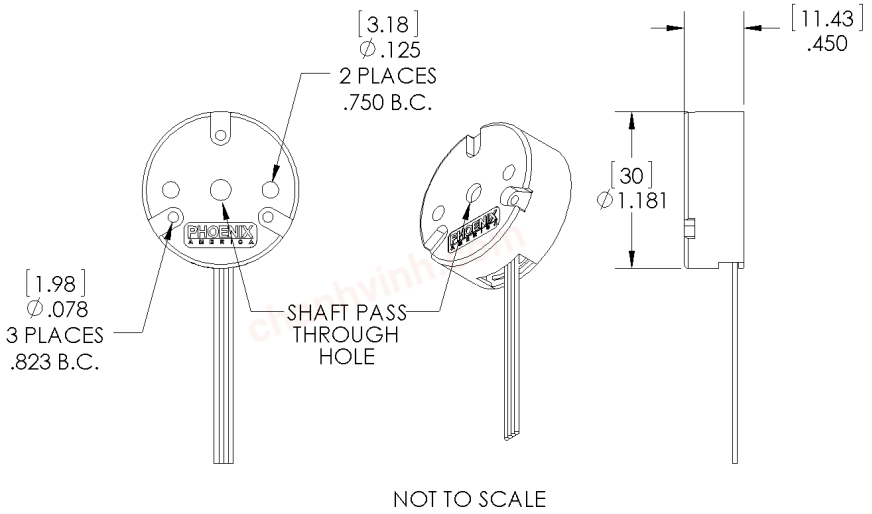


Table 4.1

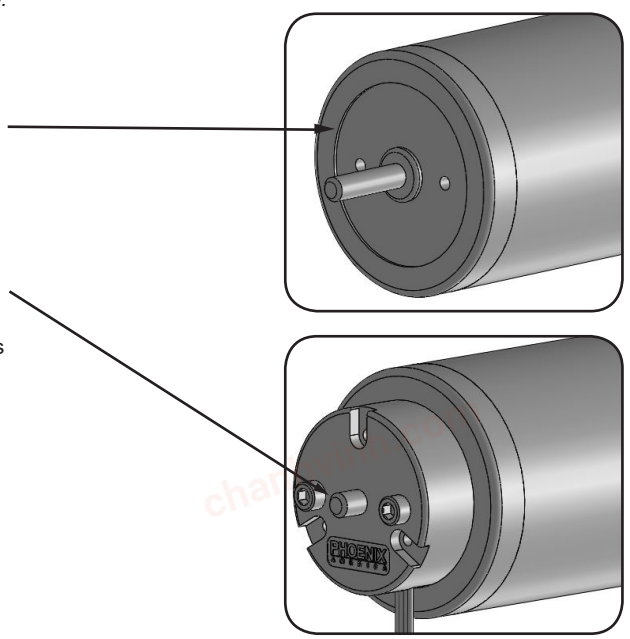
Motor Shaft Diameter	Shaft Pass Through Hole Size (options/ recommendation)	
-	No Hole	
2 mm	2.06 mm	0.081 in
3 mm	3.06 mm	0.120 in
1/8 in	3.26 mm	0.127 in
5/32 in	4.06 mm	0.160 in
4 mm	4.06 mm	0.160 in
3/16 in	4.83 mm	0.190 in
5 mm	5.06 mm	0.199 in
6 mm	6.06 mm	0.239 in
1/4 in	6.40 mm	0.252 in
7 mm	7.06 mm	0.278 in
5/16 in	8.05 mm	0.317 in
8 mm	8.05 mm	0.317 in
3/8 in	9.59 mm	0.378 in

Other shaft pass through hole sizes available upon request. Contact sales@phoenixamerica.com.

Encoder Mounting Guidelines

Concentricity of the encoder housing to the magnet rotor is critical for optimal encoder performance. Considering the following during the design phase will ensure concentricity and ease of assembly.

- Tight molding tolerances allow for the outside diameter of the encoder to be used to locate the encoder housing concentric to the motor shaft and magnet rotor. A machined pocket on the motor endbell works well for alignment. Recommended pocket is 0.015” to 0.020” deep and 2.11” in diameter.
- Extending the shaft through the optional shaft pass through hole is an easy way to align the encoder housing to the motor shaft and magnet rotor. Simply position the encoder so that the shaft is centered concentrically in the shaft pass through hole.
- If previous two methods of alignment are not used it is recommended that the encoder be fastened to the motor using #5-40 or M3 mounting screws. The slightly larger diameter of the #5-40 and M3 screws will compensate for some of the tolerance allowed when using the standard recommended #4-40 or M2.5 mounting screws.



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Target Rotor Physical Outline - Engineered Polymer Hub (Mounting Style H)

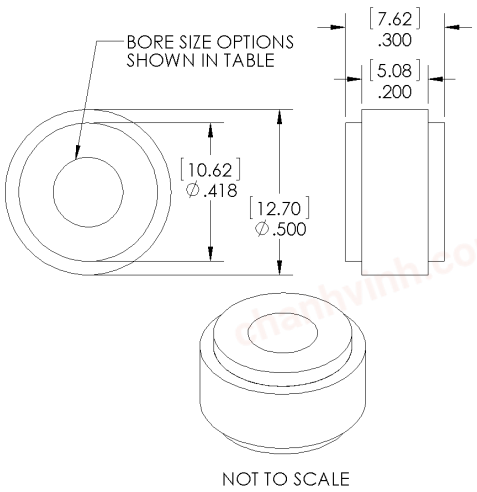


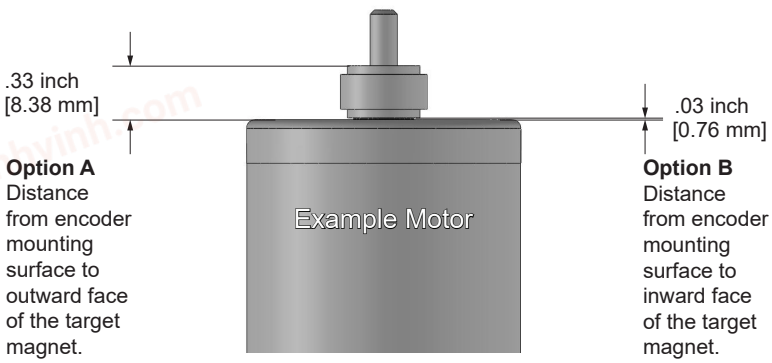
Table 5.1

Bore Size (.inch)	Motor Shaft OD Size (nominal)	NEMA Guide Shaft Tolerance	Magnet Bore MIN. (inch)	Magnet Bore MAX. (inch)
079	2 mm (.0787")	+0.0000"/-0.0005"	.0727	.0757
118	3 mm (.1181")		.1121	.1151
125	1/8 in (.1250")		.1190	.1220
156	5/32 in (.1563")		.1503	.1533
157	4 mm (.1575")		.1515	.1545
188	3/16 in (.1875")		.1815	.1845
197	5 mm (.1969")		.1909	.1939
236	6 mm (.2364")		.2304	.2334
250	1/4 in (.2500")		.2440	.2470
276	7 mm (.2758")		.2698	.2728
313	5/16 in (.3125")		.3065	.3095
315	8 mm (.3150")		.3090	.3120
375	3/8 in (.3750")		.3690	.3720

Other bore sizes available upon request.
Contact sales@phoenixamerica.com.

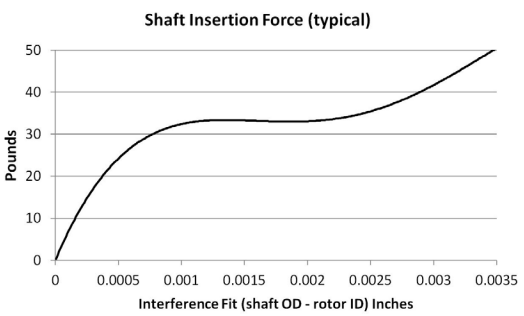
Target Rotor Mounting Guidelines - Engineered Polymer Hub (Mounting Style H) For Press Fit Application

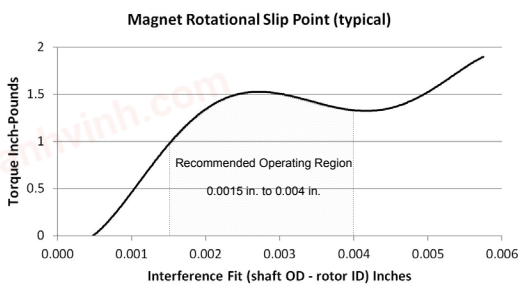
- Proper alignment of the target rotor to the encoder sensing element is critical for optimal encoder performance. Insure that the rotor is mounted to the specified height shown below.
- A machined step on the motor shaft provides a quick and repeatable method for positioning the target rotor. Spacers or other fixturing should be used if no mechanical locating features are on the shaft.
- A chamfered lead in on the shaft will aid in aligning the rotor.
- Prior to insertion, the motor shaft should be clean and free of any oils, lubricants, or solvents.
- Proper fixtures and support must be used to ensure the magnet is pressed on straight and aligned with the motor shaft.
- Opposite end of motor shaft should be supported to avoid undue stress on motor bearings during the pressing operation.
- In applications with high torque or environmental extremes, a retaining compound can be used to enhance the strength of the press fit.



Option A
Distance from encoder mounting surface to outward face of the target magnet.

Option B
Distance from encoder mounting surface to inward face of the target magnet.





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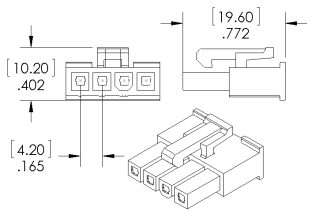
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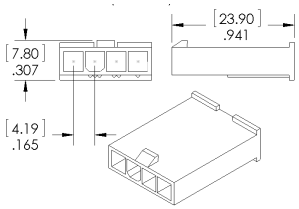
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Connector Options

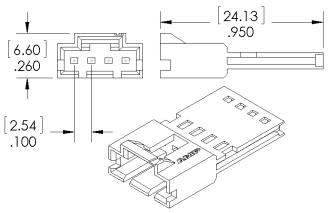
Molex Mini-Fit Jr. (Male)



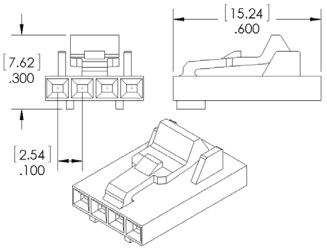
Molex Mini-Fit Jr. (Female)



TE AmpModu MTE (Male)



TE AmpModu MTE (Female)



Need a different connector? Contact sales@phoenixamerica.com.

Part Number Description

L2-10-188-N-C-N-H-F-B-X

Series	PPR	Bore Size	Index	Output Type	Shaft Pass Through Hole	Target Magnet Mounting	Wiring	Length (Meters)	Connector
L2	**4** **6** **8** **10**	**079** 2 mm **118** 3 mm **125** 1/8 in **156** 5/32 in **157** 4 mm **188** 3/16 in *(default)* **197** 5 mm **236** 6 mm **250** 1/4 in **276** 7 mm **313** 5/16 in **315** 8 mm **375** 3/8 in	**N** *A,B Quadrature (default)*	**C** *Open Collector (default)* **P** *Open Collector with Internal Pull-Up (4.7K)*	**N** *None (default)* **Y** *Size will match bore shown in Table 4.1*	**H** *Engineered Polymer Hub*	**F** *Flying Leads (default)* **C** *Cable*	**A** *.5 (19.685")* **B** 0.914 *(36") (default)* **C** 1 *(39.370")* **D** 2 *(78.740")*	**X** *None (default)* **A1** *TE AmpModu MTE (Male)* **A2** *TE AmpModu MTE (Female)* **M1** *Molex Mini-Fit Jr. (Male)* **M2** *Molex Mini-Fit Jr. (Female)*

Example: L2-10-188-N-C-N-H-F-B-X

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