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Product data sheet



DFS60I-BEPM65536

DFS60 Inox

INCREMENTAL ENCODERS

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DFS60I-BEPM65536 | DFS60 Inox

INCREMENTAL ENCODERS



Illustration may differ

Ordering information

Type	Part no.
DFS60I-BEPM65536	1083938

Other models and accessories → www.sick.com/DFS60_Inox

Detailed technical data

Performance

Pulses per revolution	16,501 ... 65,536
Measuring step	90° electric/pulses per revolution
Measuring step deviation at binary number of lines	± 0.0015°
Error limits	± 0.03°
Initialization time	32 ms [1)] 30 ms

[1)] With mechanical zero pulse width.

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL / HTL
Factory setting	Factory setting: output level TTL
Programmable/configurable	✓

Electrical data

Connection type	Cable, 8-wire, radial, 5 m
Operating current	40 mA
Power consumption	≤ 0.7 W (without load)
Supply voltage	4.5 ... 32 V
Load current	≤ 30 mA
Output frequency	≤ 820 kHz
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B

[1)] Programming TTL with ≥ 5.5 V: short-circuit opposite to another channel or GND permissable for maximum 30 s.

[2)] This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

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Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ [1]
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) [2]

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Mechanical data

Mechanical design	Blind hollow shaft
Shaft diameter	12 mm
Weight	0.5 kg
Shaft material	Stainless steel V2A
Flange material	Stainless steel V2A
Housing material	Stainless steel V2A
Start up torque	1 Ncm (+20 °C)
Operating torque	0.5 Ncm (+20 °C)
Permissible shaft movement, axial static/dynamic	± 0.5 mm / ± 0.01 mm
Permissible shaft movement, radial static/dynamic	± 0.3 mm / ± 0.05 mm
Operating speed	≤ 6,000 min^{-1} [1]
Moment of inertia of the rotor	40 gcm^2
Bearing lifetime	3.6 x 10^10 revolutions
Angular acceleration	≤ 500,000 rad/s^2

[1] Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP67, housing side (according to IEC 60529) IP67, shaft side (according to IEC 60529)
Permissible relative humidity	90 % (condensation of the optical scanning not permitted)
Operating temperature range	–40 °C ... +100 °C [1] –30 °C ... +100 °C [2]
Storage temperature range	–40 °C ... +100 °C, without package
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)
Resistance to vibration	10 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

[1] Stationary position of the cable.

[2] Flexible position of the cable.

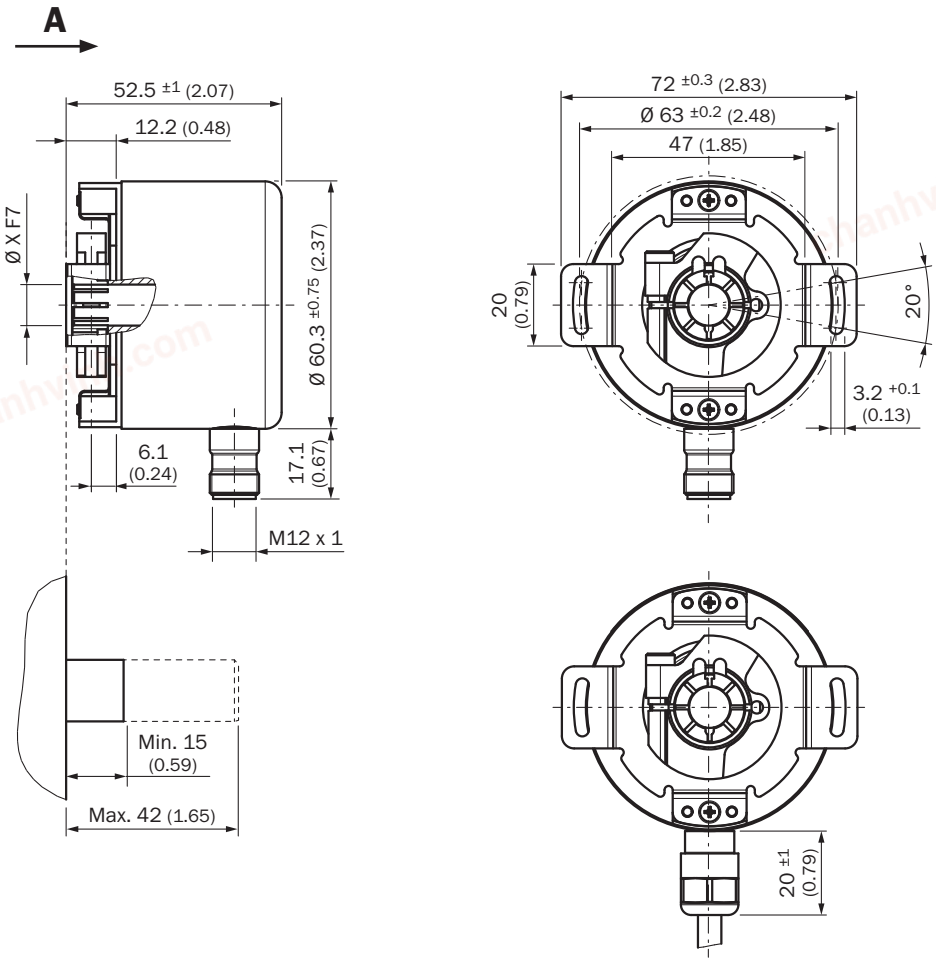
Classifications

ECl@ss 5.0	27270501
ECl@ss 5.1.4	27270501
ECl@ss 6.0	27270590
ECl@ss 6.2	27270590

ECl@ss 7.0	27270501
ECl@ss 8.0	27270501
ECl@ss 8.1	27270501
ECl@ss 9.0	27270501
ECl@ss 10.0	27270501
ECl@ss 11.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

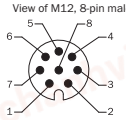
Blind hollow shaft



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PIN assignment

View of M12, 8-pin male device connector on encoder



View of M12, 12-pin male device connector on encoder

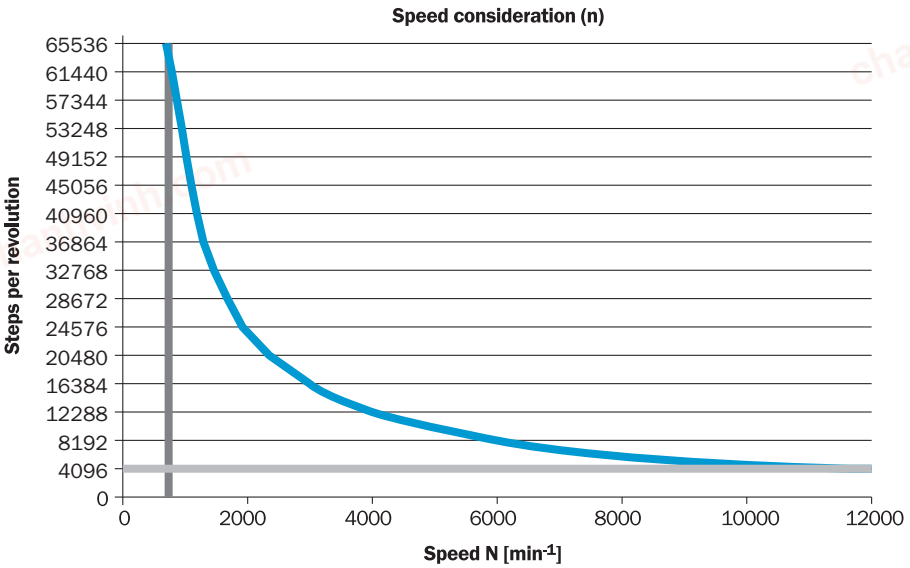


PIN, 8-pin, M12 male connector	PIN, 12-pin, M12 male connector	Color of the wires for encoders with cable outlet	TTL/HTL signal	Sin/cos 1.0 V_{ss}	Explanation
1	7	Brown	$\bar{A}$	COS–	Signal wire
2	6	White	A	COS+	Signal wire
3	9	Black	$\bar{B}$	SIN–	Signal wire
4	8	Pink	B	SIN+	Signal wire
5	4	Yellow	$\bar{Z}$	$\bar{Z}$	Signal wire
6	11	Violet	Z	Z	Signal wire
7	12	Blue	GND	GND	Ground connection of the encoder
8	5	Red	$+U_s$	$+U_s$	Supply voltage (volt-free to housing)
–	2	–	n.c.	n.c.	Not assigned
–	3	–	n.c.	n.c.	Not assigned
–	1	–	n.c.	n.c.	Not assigned
–	10 [1]	–	0-SET [1]	n.c.	Set zero pulse [1]
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

[1] For electrical interfaces only: M, V, W with 0-SET function on PIN 10 on M12 male connector. The 0-SET input is used to set the zero pulse on the current shaft position. If the 0-SET input is connected to U_s for longer than 250 ms after it had previously been unassigned for at least 1,000 ms or had been connected to the GND, the current position of the shaft is assigned to the zero pulse signal "Z".

Maximum revolution range

Maximum revolution range



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SICK AT A GLANCE

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